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Function Spaces**

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# Operator-valued Multiplication Operators on Weighted Function Spaces

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## Abstract

Let  $X$  be a completely regular Hausdorff space,  $E$  a Hausdorff topological vector space,  $V$  a Nachbin family of weights on  $X$ , and  $CV_b(X, E)$  the weighted space of continuous  $E$ -valued functions on  $X$ . Let  $B(E)$  be the vector space of all continuous linear mappings from  $E$  into itself, endowed with the topology of uniform convergence on bounded sets. If  $\psi : X \rightarrow B(E)$  is a continuous mapping and  $f \in CV_b(X, E)$ , let  $M_\psi(f) = \psi f$ , where  $(\psi f)(x) = \psi(x)(f(x))$  ( $x \in X$ ). In this paper we give a necessary and sufficient condition for  $M_\psi$  to be the multiplication operator (i.e. continuous self-mapping) on  $CV_b(X, E)$ , where  $E$  is a general space or a locally bounded space. These results extend recent work of Singh and Manhas to a non-locally convex setting and that of the authors where  $\psi$  has been considered to be a complex or  $E$ -valued map.

## 1. Introduction

The fundamental work on weighted space of continuous scalar-valued functions has been done mainly by Nachbin [5, 6] in 1960's. Since then it has been studied extensively for a variety of problems such as weighted approximation, characterization of the dual space, approximation property etc. for both scalar- and vector-valued functions (see, for instance, [1, 2, 5, 6, 7, 11]). Recently Singh and Summers [10] have studied the notion of composition operators on  $CV_b(X, E)$ . Later, Singh and Manhas [8, 9] made an analogous study of multiplication operators on  $CV_b(X, E)$ , assuming  $E$  to be a locally convex space or a normed space. This paper is a continuation of our earlier paper [3] in which we have studied, in the non-locally convex framework, multiplication operators on weighted function spaces which are induced by scalar- and vector-valued mappings.

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The purpose of this paper is to characterize those multiplication operators which are induced by operator-valued mappings. These results extend, in particular, some results of Singh and Manhas [9] for  $E$  a locally convex space or a normed space to the case of  $E$  a general space or a locally bounded space, respectively.

## 2. Preliminaries

Throughout this paper we shall assume, unless stated otherwise, that  $X$  is a completely regular Hausdorff space and  $E$  is a non-trivial Hausdorff topological vector space with a base  $\mathcal{W}$  of balanced "shrinkable" neighborhoods of 0. (A neighborhood  $G$  of 0 in  $E$  is called shrinkable [4] if  $r\overline{G} \subseteq \text{int } G$  for  $0 \leq r < 1$ . By ([4], Theorems 5 and 6), every Hausdorff topological vector space has a base of shrinkable neighborhoods of 0 and also the Minkowski functional  $\rho_G$  of any such neighborhood  $G$  is continuous.

Let  $S^+(X)$  denote the set of all non-negative upper-semicontinuous functions on  $X$ , and let  $S_0^+(X)$  ( $S_c^+(X)$ ) be the subset of  $S^+(X)$  consisting of those functions which vanish at infinity (have compact support). A Nachbin family on  $X$  is a subset  $V$  of  $S^+(X)$  such that, for any  $x \in X$ , there is some  $v \in V$  with  $v(x) > 0$  and given  $u, v \in V$ , there exist  $w \in V$  and  $t > 0$  so that  $u, v \leq tw$  (pointwise); the elements of  $V$  are called weights. Let  $C(X, E)$  ( $C_b(X, E)$ ) be the vector space of all continuous (and bounded)  $E$ -valued functions on  $X$ , and let  $CV_b(X, E)$  denote the subspace of  $C(X, E)$  consisting of those  $f$  such that  $vf$  is bounded for each  $v \in V$ . When  $E = C$  (or  $R$ ), these spaces are denoted by  $C(X)$ ,  $C_b(X)$ , and  $CV_b(X)$ . If  $\phi \in C(X)$  and  $a \in E$ , then  $\phi \otimes a$  is a function in  $C(X, E)$  defined by  $(\phi \otimes a)(x) = \phi(x)a$  ( $x \in X$ ).

Given any Nachbin family  $V$  on  $X$ , the weighted topology  $w_v$  on  $CV_b(X, E)$  is defined as the linear topology which has a base of neighborhoods of 0 consisting of all

sets of the form

$$N(v, G) = \{f \in CV_b(X, E) : (vf)(X) \subseteq G\},$$

where  $v \in V$  and  $G \in \mathcal{W}$ ;  $CV_b(X, E)$  endowed with  $w_v$  is called a weighted space. We mention that if  $V = S_0^+(X)$ , then  $CV_b(X, E) = CV_0(X, E) = C_b(X, E)$  and  $w_v = \beta$ , the strict topology, and we write it as  $(C_b(X, E), \beta)$ ; if  $V = S_c^+(X)$ , then  $CV_b(X, E) = CV_0(X, E) = C(X, E)$  and  $w_v = k$ , the compact-open topology, and we write it as  $(C(X, E), k)$ . For more information on weighted spaces, we refer to [1-3, 5-11].

Let  $B(E)$  denote the vector space of all continuous linear mappings from  $E$  into itself, endowed with the topology of uniform convergence on bounded sets, i.e. the linear topology which has a base of neighborhoods of 0 consisting of all sets of the form

$$U(A, G) = \{T \in B(E) : T(A) \subseteq G\},$$

where  $A$  is a bounded subset of  $E$  and  $G \in \mathcal{W}$ . Given a mapping  $\psi : X \rightarrow B(E)$  and  $f \in CV_b(X, E)$ , we let  $M_\psi(f) = \psi f$ , where  $(\psi f)(x) = \psi(x)(f(x))$  ( $x \in X$ ). If  $M_\psi$  maps  $CV_b(X, E)$  into itself and is continuous, then it is called a multiplication operator on  $CV_b(X, E)$  induced by  $\psi$ .

### 3. Main Results

In this section, we first give a necessary and sufficient condition for  $M_\psi$  to be the multiplication operator on the weighted space  $CV_b(X, E)$ . We then use this characterization to show that, in case  $E$  is a locally bounded space, then  $M_\psi$  is a multiplication operator if  $\psi$  is a bounded mapping or  $V = S_c^+(X)$ . Our main result is

**Theorem 3.1.** *For any continuous mapping  $\psi : X \rightarrow B(E)$ , the following are equivalent:*

(a) For every  $v \in V$  and  $G \in \mathcal{W}$ , there exist  $u \in V$  and  $H \in \mathcal{W}$  such that

$$v(x)\rho_G(\psi(x)(y)) \leq u(x)\rho_H(y) \text{ for all } x \in X \text{ and } y \in E.$$

(b)  $M_\psi$  is a multiplication operator on  $CV_b(X, E)$ .

*Proof.* We may assume that  $\mathcal{W}$  consists of closed, balanced, and shrinkable sets.

(a)  $\Rightarrow$  (b). We first show that  $M_\psi$  maps  $CV_b(X, E)$  into itself. Let  $f \in CV_b(X, E)$ , and let  $\{x_\alpha : \alpha \in I\}$  be a net in  $X$  with  $x_\alpha \rightarrow x \in X$ . Let  $G \in \mathcal{W}$ , and let  $G_1 \in \mathcal{W}$  with  $G_1 + G_1 \subseteq G$ . Now  $\{f(x_\alpha)\}$ , being convergent, is bounded and so, by continuity of  $\psi$ , there exists an  $\alpha_1 \in I$  such that

$$\psi(x_\beta)(f(x_\alpha)) - \psi(x)(f(x_\alpha)) \in G_1 \tag{1}$$

for all  $\alpha \in I$  and all  $\beta \geq \alpha_1$ . Since  $\psi(x) : E \rightarrow E$  is a continuous linear operator, there exists an  $H \in \mathcal{W}$  such that  $\psi(x)(y) \in G_1$  for all  $y \in H$ . Choose an  $\alpha_2 \in I$  such that  $f(x_\alpha) - f(x) \in H$  for all  $\alpha \geq \alpha_2$ ; consequently,

$$\psi(x)(f(x_\alpha) - f(x)) \in G_1 \tag{2}$$

for all  $\alpha \geq \alpha_2$ . Choose  $\alpha_0 \in I$  with  $\alpha_0 \geq \alpha_1, \alpha_2$ . Then, by (1) and (2)

$$\begin{aligned} \psi(x_\beta)(f(x_\beta)) - \psi(x)(f(x)) &= \psi(x_\beta)(f(x_\beta)) - \psi(x)(f(x_\beta)) + \psi(x)(f(x_\beta)) - \\ &\quad \psi(x)(f(x)) \in G_1 + G_1 \subseteq G \end{aligned}$$

for all  $\beta \geq \alpha_0$ . Hence  $\psi f \in C(X, E)$ . To show that  $\psi f \in CV_b(X, E)$ , let  $v \in V$  and  $G \in \mathcal{W}$ . By hypothesis, there exist  $u \in V$  and  $H \in \mathcal{W}$  such that

$$v(x)\rho_G(\psi(x)(y)) \leq \rho_H(u(x)(y)) \tag{3}$$

for all  $x \in X$  and  $y \in E$ . Choose  $\lambda > 0$  such that  $u(x)f(x) \in \lambda H$  for all  $x \in X$ . Then, it follows from (3) that  $v(x)\psi(f(x)) \in \lambda G$  for all  $x \in X$ . This proves that  $\psi f \in CV_b(X, E)$ .

We next establish the continuity of  $M_\psi$ . Let  $\{f_\alpha : \alpha \in I\}$  be a net in  $CV_b(X, E)$  with  $f_\alpha \rightarrow 0$ , and let  $v \in V$  and  $G \in \mathcal{W}$ . Choose  $u \in V$  and  $H \in \mathcal{W}$  as above and which satisfy (3). There exists an  $\alpha_0 \in I$  such that  $f_\alpha \in N(u, H)$  for all  $\alpha \geq \alpha_0$ . Then, for any  $x \in X$  and  $\alpha \geq \alpha_0$ ,

$$v(x)\rho_G(\psi(x)(f_\alpha(x))) \leq u(x)\rho_H(f_\alpha(x)) \leq 1$$

or equivalently  $v(x)\psi(x)(f_\alpha(x)) \in G$ . So  $M_\psi$  is continuous at 0 and hence, by linearity, it is continuous on  $CV_b(X, E)$ .

(b)  $\Rightarrow$  (a). Let  $v \in V$  and  $G \in \mathcal{W}$ . By hypothesis, there exist  $u \in V$  and  $H \in \mathcal{W}$  such that

$$M_\psi(N(u, H)) \subseteq N(v, G). \quad (4)$$

We claim that

$$v(x)\rho_G(\psi(x)(y)) \leq 2u(x)\rho_H(y)$$

for all  $x \in X$  and  $y \in E$ . Let  $x_0 \in X$  and  $y_0 \in E$ . Then we consider four cases:

- (I)  $u(x_0)\rho_H(y_0) \neq 0$ .
- (II)  $u(x_0) = 0, \rho_H(y_0) \neq 0$ .
- (III)  $u(x_0) \neq 0, \rho_H(y_0) = 0$ .
- (IV)  $u(x_0) = 0, \rho_H(y_0) = 0$ .

**Case I.** Suppose  $u(x_0)\rho_H(y_0) \neq 0$ , and let  $\epsilon = u(x_0)\rho_H(y_0)$ . Then the set  $D = \{x \in X : u(x)\rho_H(y_0) < 2\epsilon\}$  is an open neighborhood of  $x_0$ . By ([6], p. 69), there exists an  $h \in CV_b(X)$  such that  $0 \leq h \leq 1$ ,  $h(x_0) = 1$ , and  $h(X \setminus D) = 0$ . Define  $g = (h \otimes y_0)/2\epsilon$ . Then it is easily seen that  $g \in N(u, H)$ . Hence, by (4),  $\psi g \in N(v, G)$ . This implies that, for any  $x \in X$ ,

$$v(x)h(x)\rho_G(\psi(x)(y_0)) \leq 2u(x_0)\rho_H(y_0).$$

In particular, by taking  $x = x_0$ , we have

$$v(x_0)\rho_G(\psi(x_0)(y_0)) \leq 2u(x_0)\rho_H(y_0).$$

**Case II.** Suppose  $u(x_0) = 0$  but  $v(x_0)\rho_G(\psi(x_0)(y_0)) > 0$ . Put  $\epsilon = v(x_0)\rho_G(\psi(x_0)(y_0))/2$ . Then, by the arguments used in Case I with  $D = \{x \in X : u(x)\rho_H(y_0) < \epsilon\}$  and  $g = (h \otimes y_0)/\epsilon$ , we easily obtain

$$v(x_0)\rho_G(\psi(x_0)(y_0)) \leq 2v(x_0)\rho_G(\psi(x_0)(y_0))$$

which is impossible unless  $v(x_0)\rho_G(\psi(x_0)(y_0)) = 0$ . The proofs for Cases III and IV, being similar to Case II, are omitted. This completes the proof.

We now deduce that, under some additional conditions on  $\psi$ ,  $M_\psi$  is automatically a multiplication operator.

**Corollary 3.2.** *Let  $\psi : X \rightarrow B(E)$  be a constant mapping. Then  $M_\psi$  is a multiplication operator on  $CV_b(X, E)$ .*

*Proof.* We need to verify that condition (a) of Theorem 3.1 holds in this case. Let  $v \in V$  and  $G \in \mathcal{W}$ . Choose  $T \in B(E)$  such that  $\psi(x) = T$  for all  $x \in X$ . Choose

a closed and shrinkable  $H \in \mathcal{W}$  with  $H \subseteq G$ . Since  $T$  being continuous and linear, is bounded, there exists  $m > 0$  such that  $T(E) \subseteq mH$  i.e.  $\rho_H(\psi(x)(y)) \leq m$  for all  $x \in X$  and  $y \in E$ . Let  $u = mv$ . Then, for any  $x \in X$  and  $y \in E$ .

$$\begin{aligned} v(x)\rho_G(\psi(x)(y)) &\leq v(x)\rho_H(\psi(x)(y)) \\ &\leq u(x)\rho_H(y), \end{aligned}$$

as required.

**Corollary 3.3.** *Suppose  $E$  is a locally bounded space and  $\psi : X \rightarrow B(E)$  is a continuous and bounded mapping. Then  $M_\psi$  is a multiplication operator on  $CV_b(X, E)$ .*

*Proof.* Let  $v \in V$  and  $G \in \mathcal{W}$ . We may assume that  $G$  is a bounded neighborhood of 0. Choose a closed and shrinkable  $H \in \mathcal{W}$  with  $H \subseteq G$ . Since  $\psi(X)$  is bounded in  $B(E)$ , there exists  $m > 0$  such that  $\psi(X) \subseteq mU(H, H)$ ; i.e.,

$$\rho_H(\psi(x)(y)) \leq m \text{ for all } x \in X \text{ and } y \in H.$$

Let  $u = mv$ . Then, for any  $x \in X$  and  $y \in E$ ,

$$\begin{aligned} v(x)\rho_G(\psi(x)(y)) &\leq v(x)\rho_H(\psi(x)(y)) \\ &\leq u(x)\rho_H(y). \end{aligned}$$

This completes the proof.

Finally, we apply Theorem 3.1 to the cases  $V = S_c^+(X)$  and  $V = S_0^+(X)$ . The following result with  $E$  being a locally bounded space extends ([9], Proposition 2.3) where  $E$  has been taken to be a normed space.

**Theorem 3.4.** *Suppose  $E$  is a locally bounded space and  $\psi : X \rightarrow B(E)$  is a*



continuous mapping. Then  $M_\psi$  is a multiplication operator on  $(C(X, E), k)$ .

*Proof.* We need to verify that condition (a) of Theorem 3.1 holds for  $V = S_c^+(X)$ . Let  $v \in V$  and  $G \in \mathcal{W}$ . Choose a compact  $K \subseteq X$  such that  $v(x) = 0$  for all  $x \in X \setminus K$ . We may assume that  $G$  is a bounded neighborhood of 0. Choose a closed and shrinkable  $H \in \mathcal{W}$  with  $H \subseteq G$ . Since  $\psi : X \rightarrow B(E)$  is continuous,  $\psi(K)$  is compact in  $B(E)$  and so there exists  $m > 0$  such that  $\psi(K) \subseteq mu(H, H)$ ; i.e.

$$\rho_H(\psi(x)(y)) \leq m \text{ for } x \in K \text{ and } y \in H.$$

Let  $t = \sup\{v(x) : x \in K\}$ , and put  $u = mt\chi_K$ . Then  $u \in V$ . Let  $x \in X$  and  $y \in E$ .

If  $x \in K$ , then

$$\begin{aligned} v(x)\rho_G(\psi(x)(y)) &\leq t\rho_H(\psi(x)(y)) \\ &\leq u(x)\rho_H(y). \end{aligned}$$

If  $x \in X \setminus K$ , the above holds trivially (since  $v(x) = 0$ ). This completes the proof.

The following example shows that the above result need not hold when  $(C(XE), k)$  is replaced by  $(C_b(X, E), \beta)$ .

**Example 3.5.** Let  $X = \mathbb{R}^+$ ,  $E = \mathbb{C}$ , and  $V = S_0^+(X)$ . Let  $\psi : X \rightarrow B(E) = \mathbb{C}$  be given by  $\psi(x) = x^2$  ( $x \in X$ ), and let  $v \in V$  be given by  $v(x) = \frac{1}{x}$  ( $x \in X$ ). Then  $v(x)|\psi(x)| = x$  for all  $x \in X$ . Since each  $u \in V$  is a bounded function,  $v|\psi| \leq u$  for all  $u \in V$ . Hence, by Theorem 3.1,  $M_\psi$  is not a multiplication operator on  $(C_b(X), \beta)$ .

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