

(9) Solve the Initial Value Problem:

[11 points]

$$y''' + 2y'' + 9y' + 18y = 0 \text{ subject to } y(0) = 0, \quad y'(0) = 2 \text{ and } y''(0) = -13$$

Given that one solution of the differential equation is $y(x) = e^{-2x}$.

The characteristic eqn of the differential eqn is: $r^3 + 2r^2 + 9r + 18 = 0$ 1 pt

Since we're given the information that $y(x) = e^{-2x}$ is a solution

we know that $r = -2$ 1 pt is a root of the ch. eqn.

By dividing the ch. eqn by $r+2$, we can find the other roots

$$\left. \begin{array}{r} r^2 + 9 \\ r+2 \overline{) r^3 + 2r^2 + 9r + 18} \\ \underline{r^3 + 2r^2} \\ 9r + 18 \\ \underline{-9r + 18} \\ 0 \end{array} \right\} r^3 + 2r^2 + 9r + 18 = (r+2)(r^2 + 9) = 0 \quad \text{1 pt}$$

So the roots of the ch. eqn are $r_1 = -2$ $r_{2,3} = \pm 3i$ 1 pt

Then the general solution is of the form:

$$y(x) = C_1 e^{-2x} + C_2 \cos(3x) + C_3 \sin(3x). \quad \text{3 pts}$$

To find C_1 , C_2 , and C_3 , we use the initial conditions:

$$y'(x) = -2C_1 e^{-2x} - 3C_2 \sin(3x) + 3C_3 \cos(3x) \quad \text{1 pt}$$

$$y''(x) = 4C_1 e^{-2x} - 9C_2 \cos(3x) - 27C_3 \sin(3x). \quad \text{1 pt}$$

$$\begin{array}{l} y(0) = C_1 + C_2 = 0 \\ y'(0) = -2C_1 + 3C_3 = 2 \\ y''(0) = 4C_1 - 9C_2 = -13 \end{array} \quad \Rightarrow \quad \begin{array}{l} C_1 = -1 \\ C_2 = 1 \\ C_3 = 0 \end{array} \quad \text{1 pt}$$

Then the general solution is:

$$y(x) = -e^{-2x} + \cos(3x) \quad \text{1 pt}$$

(10) If the complimentary solution of the differential equation

[10 points]

$$y'' - 2y' + 17y = xe^x \cos 4x \text{ is } y_c = e^x (A \cos 4x + B \sin 4x),$$

write the form of the particular solution of the differential equation. (Do not determine constants).

Call $f(x) = xe^x \cos 4x$.

Based on $f(x)$, the first version of a particular solution

should be $y_p(x) = \underline{xe^x(A \cos 4x + B \sin 4x)} + e^x(C \cos 4x + D \sin 4x)$

(3 pts) (3 pts)

We observe that $e^x(C \cos 4x + D \sin 4x)$ is duplicating
in y_p and y_c . (1 pt)

To remove the duplication, we multiply it by x . (2 pts)

Then the particular solution is of the form:

$$y_p(x) = x^2 e^x (A \cos 4x + B \sin 4x) + x e^x (C \cos 4x + D \sin 4x) \quad (1 \text{ pt})$$

(11) Using the method of variation of parameters solve the Initial Value Problem [13 points]

$$(x^2 - 1)y'' + 4xy' + 2y = \frac{2}{x+1}, \quad y(0) = -1, \quad y'(0) = -5$$

Given that $y_1 = \frac{1}{x-1}$ and $y_2 = \frac{1}{x+1}$ are solutions of the homogenous part.

We rewrite the differential eqn: $y'' + \frac{4x}{x^2-1}y' + \frac{2}{x^2-1}y = \frac{2}{(x^2-1)(x+1)}$

$$W(y_1, y_2) = \begin{vmatrix} (x-1)^{-1} & (x+1)^{-1} \\ -1(x-1)^{-2} & -1(x+1)^{-2} \end{vmatrix} = (x-1)^{-2}(x+1)^{-1} - (x-1)^{-1}(x+1)^{-2}$$

(2 pts)

$$= (x-1)^{-2}(x+1)^{-2}(x+1 - (x-1))$$

$$= 2(x-1)^{-2}(x+1)^{-2} \quad (1 \text{ pt})$$

$$y_p = \left(- \int \frac{(x+1)^{-1} \cdot 2(x+1)^{-2}(x-1)^{-1}}{2(x-1)^{-2}(x+1)^{-2}} dx \right) \frac{1}{x-1} + \left(\int \frac{(x-1)^{-1} \cdot 2(x+1)^{-2}(x-1)^{-1}}{2(x-1)^{-2}(x+1)^{-2}} dx \right) \frac{1}{x+1}$$

(1 pt) (1 pt)

$$y_p = \left(- \int \frac{x-1}{x+1} dx \right) \frac{1}{x-1} + \left(\int dx \right) \frac{1}{x+1}$$

(1 pt) (1 pt)

$$y_p = (-x + 2 \ln(x+1)) \frac{1}{x-1} + \frac{x}{x+1} = \frac{2 \ln(x+1)}{x-1} - \frac{2x}{x^2-1} \quad (1 \text{ pt})$$

Then a general solution is of the form:

$$y(x) = \frac{C_1}{x-1} + \frac{C_2}{x+1} + \frac{2 \ln(x+1)}{x-1} - \frac{2x}{x^2-1} \quad (1 \text{ pt})$$

To find C_1 and C_2 , we use the initial conditions

$$y'(x) = \frac{-C_1}{(x-1)^2} + \frac{C_2}{(x+1)^2} + \frac{\frac{2}{x+1} \cdot (x-1) + 2 \ln(x+1)}{(x-1)^2} - \frac{2(x^2-1) - 4x^2}{(x^2-1)^2} \quad (1 \text{ pt})$$

$$y(0) = -C_1 + C_2 = -1$$

$$y'(0) = -C_1 - C_2 - 2 + 2 = -5$$

$$\Rightarrow \begin{cases} -C_1 + C_2 = -1 \\ -C_1 - C_2 = -5 \end{cases} \Rightarrow C_1 = 3 \quad (1 \text{ pt})$$

$$C_2 = 2 \quad (1 \text{ pt})$$

Then the general solution is

$$y(x) = \frac{3}{x-1} + \frac{2}{x+1} + \frac{2 \ln(x+1)}{x-1} - \frac{2x}{x^2-1} \quad (1 \text{ pt})$$

(12) Suppose that the matrix $A = \begin{pmatrix} 2 & 2 & 3 \\ 1 & 2 & 1 \\ 2 & -2 & 1 \end{pmatrix}$ is diagonalizable with eigenvalues

$\lambda_1 = -1$, $\lambda_2 = 2$, $\lambda_3 = 4$. Find two matrices P & D so that $A = PDP^{-1}$ [12 points]

The eigenvalues are already given. We need to find next eigenvectors.

eigenvector assoc. to $\lambda = -1$:

We solve the system $(A + I)v = 0$.

$$\begin{bmatrix} 3 & 2 & 3 \\ 1 & 3 & 1 \\ 2 & -2 & 2 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \xrightarrow{\text{after row operations}} \begin{bmatrix} 1 & 3 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \Rightarrow \begin{aligned} a + 3b + c &= 0 \\ b &= 0. \end{aligned}$$

Choose $a = t$. Then $c = -t$.

The eigenvector assoc. to $\lambda = -1$ is $v_1 = \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}$.

eigenvector assoc. to $\lambda = 2$:

We solve the system $(A - 2I)v = 0$.

$$\begin{bmatrix} 0 & 2 & 3 \\ 1 & 0 & 1 \\ 2 & -2 & -1 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \xrightarrow{\text{after row operations}} \begin{bmatrix} 1 & 0 & 1 \\ 0 & 2 & 3 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \Rightarrow \begin{aligned} a + c &= 0 \\ 2b + 3c &= 0 \end{aligned}$$

Choose $c = 2t$. Then $b = -3t$ and $a = -2t$.

The eigenvector assoc to $\lambda = 2$ is $v_2 = \begin{bmatrix} -2 \\ -3 \\ 2 \end{bmatrix}$.

eigenvector assoc. to $\lambda = 4$:

We solve the system $(A - 4I)v = 0$.

$$\begin{bmatrix} -2 & 2 & 3 \\ 1 & -2 & 1 \\ 2 & -2 & -3 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \xrightarrow{\text{after row operations}} \begin{bmatrix} 1 & -2 & 1 \\ 0 & -2 & 5 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \Rightarrow \begin{aligned} a - 2b + c &= 0 \\ -2b + 5c &= 0 \end{aligned}$$

Choose $c = 2t$. Then $b = 5t$ and $a = 8t$.

The eigenvector assoc to $\lambda = 4$ is $v_3 = \begin{bmatrix} 8 \\ 5 \\ 2 \end{bmatrix}$.

Then $P = \begin{bmatrix} 1 & -2 & 8 \\ 0 & -3 & 5 \\ -1 & 2 & 2 \end{bmatrix}$ and $D = \begin{bmatrix} -1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 4 \end{bmatrix}$

(2 pts)

(1 pt)

(3 pts)

(3 pts)

(3 pts)

(13) Consider the matrix $A = \begin{pmatrix} 1 & 2 & 2 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{pmatrix}$, use Cayley-Hamilton Theorem to find

A^3 and A^{-1} .

[10 points]

We find the characteristic polynomial of A

$$p(\lambda) = |A - \lambda I| = \begin{vmatrix} 1-\lambda & 2 & 2 \\ 0 & 1-\lambda & 2 \\ 0 & 0 & 1-\lambda \end{vmatrix} = (1-\lambda)^3 \quad (1 \text{ pt})$$

Then by Cayley-Hamilton Theorem, $p(A) = (I - A)^3 = 0$ (3 pts)

$$I - 3A + 3A^2 - A^3 = 0 \Rightarrow A^3 = 3A^2 - 3A + I \quad (1 \text{ pt})$$

$$A^2 = \begin{bmatrix} 1 & 2 & 2 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 & 2 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 4 & 8 \\ 0 & 1 & 4 \\ 0 & 0 & 1 \end{bmatrix} \quad (1 \text{ pt})$$

$$A^3 = 3 \begin{bmatrix} 1 & 4 & 8 \\ 0 & 1 & 4 \\ 0 & 0 & 1 \end{bmatrix} - 3 \begin{bmatrix} 1 & 2 & 2 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{bmatrix} + \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 6 & 18 \\ 0 & 1 & 6 \\ 0 & 0 & 1 \end{bmatrix} \quad (1 \text{ pt})$$

To find A^{-1} , we solve $p(A) = 0$ for I .

$$I = 3A - 3A^2 + A^3 \quad (1 \text{ pt})$$

We multiply both sides by A^{-1} .

$$A^{-1} = 3I - 3A + A^2$$

$$= 3 \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} - 3 \begin{bmatrix} 1 & 2 & 2 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{bmatrix} + \begin{bmatrix} 1 & 4 & 8 \\ 0 & 1 & 4 \\ 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & -2 & 2 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{bmatrix} \quad (1 \text{ pt})$$

- (14) Consider the homogenous system $X'(t) = \begin{pmatrix} 6 & 4 & 4 \\ -7 & -2 & -1 \\ 7 & 4 & 3 \end{pmatrix} X(t)$. [10 points]

a) Verify that $X_1(t) = \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} e^{6t}$ is a solution of the system.

b) Verify that the solutions $X_1(t) = \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} e^{6t}$, $X_2(t) = \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix} e^{2t}$, $X_3(t) = \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix} e^{-t}$

are linearly independent.

- c) Find a general solution of the system.

a) $X_1'(t) = \begin{bmatrix} 6 \\ -6 \\ 6 \end{bmatrix} e^{6t}$ (1pt)

$$\begin{bmatrix} 6 & 4 & 4 \\ -7 & -2 & -1 \\ 7 & 4 & 3 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} e^{6t} = \begin{bmatrix} 6-4+4 \\ -7+2-1 \\ 7-4+3 \end{bmatrix} e^{6t} = \begin{bmatrix} 6 \\ -6 \\ 6 \end{bmatrix} e^{6t}$$
 (1pt)

So $X_1(t)$ is a solution.

b)

$$W(X_1, X_2, X_3) = \begin{vmatrix} e^{6t} & e^{2t} & 0 \\ -e^{6t} & -2e^{2t} & -e^{-t} \\ e^{6t} & e^{2t} & e^{-t} \end{vmatrix} = e^{6t} \begin{vmatrix} -2e^{2t} & -e^{-t} \\ e^{2t} & e^{-t} \end{vmatrix} - e^{2t} \begin{vmatrix} -e^{6t} & -e^{-t} \\ e^{6t} & e^{-t} \end{vmatrix}$$

(2pts)

$$= e^{6t} (-2e^t + e^t) - e^{2t} (-e^{5t} + e^{5t}) = -e^{7t} \neq 0$$

(1pt) (1pt)

Then X_1, X_2 , and X_3 are linearly independent. (1pt)

c) $X(t) = c_1 X_1(t) + c_2 X_2(t) + c_3 X_3(t)$

$$X_1(t) = c_1 e^{6t} + c_2 e^{2t}$$
 (1pt)

$$X_2(t) = -c_1 e^{6t} - 2c_2 e^{2t} - e^{-t}$$
 (1pt)

$$X_3(t) = e^{6t} + e^{2t} + e^{-t}$$
 (1pt)

- (15) Find a general solution of the system $X' = \begin{pmatrix} 1 & -1 & 2 \\ -1 & 1 & 0 \\ -1 & 0 & 1 \end{pmatrix} X$. [13 points]

We first find all eigenvalues and eigenvectors.

Call $A = \begin{bmatrix} 1 & -1 & 2 \\ -1 & 1 & 0 \\ -1 & 0 & 1 \end{bmatrix}$.

$$|A - \lambda I| = \begin{vmatrix} 1-\lambda & -1 & 2 \\ -1 & 1-\lambda & 0 \\ -1 & 0 & 1-\lambda \end{vmatrix} = -\lambda^3 + 3\lambda^2 - 4\lambda + 2 = 0 \quad (1 \text{ pt})$$

eigenvalues are $\lambda_1 = 1$ $\lambda_{2,3} = 1 \pm i$ (1 pt)

eigenvector assoc to $\lambda_1 = 1$:

We solve the system $(A - I)v = 0$ and find that $v_1 = \begin{bmatrix} 0 \\ 2 \\ 1 \end{bmatrix}$ (2 pts)

eigenvector assoc to $\lambda_2 = 1 + i$:

We solve the system $(A - (1+i)I)v = 0$ and find that $v_2 = \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$ (2 pts)

eigenvector assoc to $\lambda_3 = 1 - i$: is complex conjugate of the

eigenvector assoc to $\lambda_2 = 1 + i$. So $v_3 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$ (2 pts)

a general solution is:

$$X(t) = c_1 e^t v_1 + c_2 e^{(1+i)t} v_2 + c_3 e^{(1-i)t} v_3$$

$$x_1(t) = (-c_2 + c_3) e^t \cos t + (c_2 + c_3) e^t \sin t$$

$$x_2(t) = 2c_1 e^t + (c_2 + c_3) e^t \cos t + (-c_2 + c_3) e^t \sin t.$$

$$x_3(t) = c_1 e^t + (c_2 + c_3) e^t \cos t + (-c_2 + c_3) e^t \sin t.$$

(3 pts)

(16) Find a general solution of the system $X' = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} X$. [13 points]

We first find all eigenvalues and eigenvectors.

Call $A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$.

$$|A - \lambda I| = \begin{vmatrix} \lambda & 1 & 0 \\ 0 & -\lambda & 0 \\ 0 & 0 & 1-\lambda \end{vmatrix} = \lambda^2(1-\lambda) = 0 \quad (1 \text{ pt})$$

eigenvalues are $\lambda_1 = 0$ (multiplicity 2) and $\lambda_2 = 1$ (1 pt)
eigenvector assoc. $\lambda_1 = 0$ (1 pt)

We solve the system $Av = 0$ and find that $v_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ (1 pt)

Then the eigenvalue $\lambda_1 = 0$ is defective with defect = $2 - 1 = 1$.

We need to find a length 2 chain of generalized eigenvectors generated by v_1 . That is a set $\{u_1, u_2\}$ of vectors where $A^2 u_2 = 0$ and $Au_2 = u_1$

$$A^2 = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad \text{so choose } u_2 = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \quad (1 \text{ pt})$$

$$u_1 = Au_2 = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \quad (1 \text{ pt})$$

eigenvector assoc. to $\lambda_2 = 1$:

We solve the system $(A - I)v = 0$ and find that $v_2 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$.

Then the general solution is:

$$X(t) = c_1 u_1 + c_2(u_1 t + u_2) + c_3 e^t v_2 \quad (2 \text{ pts})$$

$$\begin{array}{l} x_1(t) = c_1 + c_2(t+1) \\ x_2(t) = c_2 \\ x_3(t) = c_3 e^t \end{array} \quad \left| \rightarrow (2 \text{ pts}) \right.$$